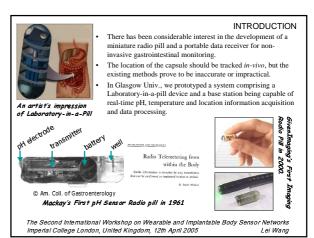
A MULTI-PARAMETER LABORATORY-IN-A-PILL DEVICE WITH REAL-TIME DATA PROCESSING

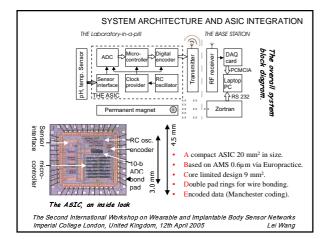
L. Wang, E. A. Johannessen, A. Bradley, S. Borthwick, J. M. Cooper, and D. R. S. Cumming

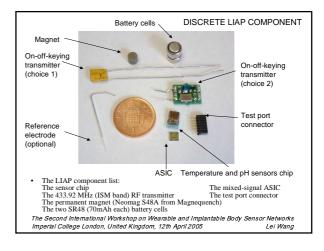
The University of Glasgow, United Kingdom

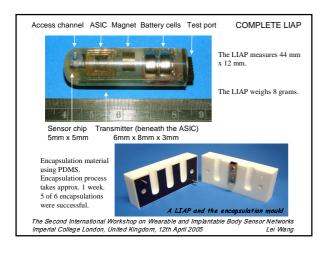
Honeywell Automation and Control Solutions, United Kingdom

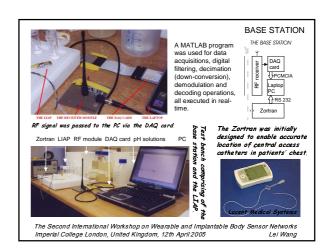
The Second International Workshop on Wearable and Implantable Body Sensor Networks Imperial College London, United Kingdom, 12th April 2005 Lei Wang

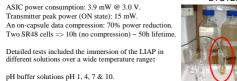












- Artificial gastric & intestinal solutions. Artificial (high viscosity) GI solutions.
- PBS & RO water.

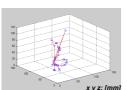
Temperature ranged 10°C ~ 50°C using a feedback-controllable hotplate.

controllable hotplate.			The LIAP (ext. powered) immersed into one test soluti		
	Buffered pH solutions	Artificial GI solutions	Artificial GI solutions (high viscosity)		
pH channel resolution (pH)	0.1	0.4	0.3		
pH channel response time (s)	5.7	15.8	2400		
On-capsule compression ratio	2.9	3.5	2.8		

SYSTEM TEST

The Second International Workshop on Wearable and Implantable Body Sensor Networks Imperial College London, United Kingdom, 12th April 2005 Lei Wang

	Gastric	grated AgCl references & Intestinal Juice Sc	e, ext Power olution	TURE	AND pH TES
	Di	ry storage prior to us	8		
1	10 Gastric	Gastric testinal	∍∥- Intestinal	⊤ 30	2 7
	8			- 25	he LIA vrificia
	6			- 20	2.0
#	°]			ر 20	I's
oH / unit	4 -			- 15 g	9 e
표		:	Ī ,	ļ Þ	was exposed GI solutions 1
	2 -	Ĺ	Î	- 10	۶ <u>د</u>
	0 -		Run 3	- 5	\$ =
	Run 1	Run 2		-	<u>w</u>
	0 20 40 6		140 160 180 2	[⊥] 0	0 1
	0 20 40 6	Time / min	140 160 160 2	:00	
	curve: temperature			rve: pH	
	cial gastric solution ental temperature 2:		iciai intestinai	solution	рн 6.8,
	ings in intestinal so		ad at nU 5.6 th	at was lo	war than the
	the deep access and				
					ensor Networks

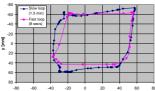


Location information displayed in real time using the MATLAB program.

Since the LIAP is expected to travel in the small intestine at an average speed of 2 cm/min ~ 5 cm/min, the response time of the location tracking would be sufficient.

LOCATION TRACKING TEST

- The magnet was moved at approximately 10 cm/min and 150 cm/min, respectively, and the position information from Zortran was presented (below).
- The test also showed a location accuracy of ± 1 cm was achieved within 25 cm distance. For distance less than 10 cm a better accuracy of ± 0.5 cm was achieved.



The Second International Workshop on Wearable and Implantable Body Sensor Networks Imperial College London, United Kingdom, 12th April 2005 Lei Wang

CONCLUSION

- $\bullet \quad \textit{Outputs from the 8-month Laboratory-in-a-pill feasibility project:} \\$
- Sensors: proven functionality within buffered and simulated GI environment.
- ASIC: self-timed, low power consumption, more functionalities could be added.
- LIAP: low cost encapsulation, size needs further reduction.
- $\bullet \quad \textit{Base station} \text{: being capable of real time data processing, need to be hardwared.} \\$
- Location tracking: there is a potential (location tracking due to a permanent magnet), but more research are required, e.g. earth field effects when ambulatory.
- Wireless link: an easy and cheap way to achieve a 10 kbps data link.
- In the future:
- Validation of the system performance in real GI tract. Demonstration the safety for ingestion.
- In vivo trials on animals

The Second International Workshop on Wearable and Implantable Body Sensor Networks Imperial College London, United Kingdom, 12th April 2005 Lei Wang