

Clinical Abstract Format for the Hamlyn Symposium on Medical Robotics

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ABSTRACT

The 5th Hamlyn Symposium for Medical Robotics will be held on 1st and 2nd July at The Royal Geographical Society in London, UK. Situated in South Kensington, the Royal Geographical Society is only a short walk away from The Hamlyn Centre and from London's top Museums. The focus of the symposium is to explore new challenges and opportunities of medical robotics in Engineering, Medicine and Natural Sciences.

Topics to be addressed by the symposium include, but are not limited to: Clinical highlights in Urology, Cardiac Surgery, Thoracic Surgery, General Surgery, Gynaecology, ENT, and Paediatric Surgery; Emerging, multi-specialty applications of robotic technology; Medical robotics for NOTES; Mechatronic designs for medical robotics; Microbot design and applications; Surgical simulation, training and skills assessment; Human robot interaction and ergonomics; Surgical navigation and augmented reality systems; Intra-operative imaging and biophotonics for robotic surgery; Robotic assisted multi-scale image fusion and visualization; Medical image computing and computer assisted intervention; Economic and general consideration of robotic surgery.

Completed papers should be submitted as a pdf-file via the online submission at: <http://www.hamlyn-robotics.org>. Please contact the following e-mail address with any questions: hamlyn-robotics@imperial.ac.uk.

- **Clinical Abstract Length:** Maximum 500 words plus 2 figures/tables;
- **Paper size:** DIN A4 Size (210 mm x 297 mm);
- **Rand:** Leave a 25mm margin at top and bottom of the page, and a 20mm margin at left and right sides.
- **Font properties and size:** Title: 14 pt, bold; Authors: 14 pt, normal; Institute + E-mail address: 12 pt, italics; Section headings: 10 pt, Capitals, bold; Text: 10 pt, normal; Figure captions and references: 9pt, normal.



Fig. 1 We are the UK's learned society and professional body for geography, founded in 1830. We advance geography and support its practitioners in the UK and across the world.

REFERENCES

- [1] Author AN, Co-Author B. Laser-induced fluorescence and reflected white light imaging for robot-assisted MIS. IEEE Trans Biomed Eng. 2009 Mar;56(3):889-92.
- [2] Co-author B. Gaze-contingent motor channeling and haptic constraints for minimally invasive robotic surgery. Med Image Comput Comput Assist Interv. 2008;11(Pt 2):676-83.